

Linear algebra 1R, problem sheet 11

1. Prove: $\ker(F \circ G) \supseteq \ker(G)$, $\text{Im}(F \circ G) \subseteq \text{Im}(F)$ where F, G are linear transformations.
2. Find nonparametric equations describing images and kernels of transformations $\mathbf{R}^n \rightarrow \mathbf{R}^k$ given by matrices:

$$\begin{pmatrix} 1 & -2 & 3 \\ -3 & 6 & -9 \end{pmatrix}; (5 \quad -1 \quad 2); \begin{pmatrix} 5 \\ -1 \\ 2 \end{pmatrix}; \begin{pmatrix} 1 & 0 & 3 \\ 3 & -1 & 0 \\ 1 & 1 & 2 \end{pmatrix};$$

3. Find general form of solution of $AX = Y$ (a) for: $A = \begin{pmatrix} 1 & 2 & -1 \\ 2 & -1 & 1 \\ 7 & -4 & 1 \end{pmatrix}$, $\begin{pmatrix} 1 & 3 & -2 \\ 3 & 9 & -6 \\ -2 & -6 & 4 \end{pmatrix}$;
 $Y = (0, 0, 0)^\top, (1, 1, 1)^\top, (1, -2, 3)^\top, (-6, -3, 3)^\top, (2, 4, 2)^\top$,
 $(-1, 3, 0)^\top, (1, 0, 3)^\top, (1, 3, 0)^\top, (4, 12, -8)^\top$; (b) for $A = \begin{pmatrix} 1 & -2 & 3 \\ -3 & 6 & -9 \end{pmatrix}$; $Y = \begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 2 \\ 0 \end{pmatrix}, \begin{pmatrix} -5 \\ 15 \end{pmatrix}, \begin{pmatrix} 90 \\ -30 \end{pmatrix}$.

4. Prove: if $AX = Y$ has two solutions, then it has infinitely many solutions.

5. Find M^{-1} . Try all methods known to you: $M =$

$$\begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}; \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}; \begin{pmatrix} 5 & 5 & 1 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}; \begin{pmatrix} 1 & 2 & 3 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{pmatrix}; \begin{pmatrix} 1 & -1 & 2 \\ 6 & 0 & 1 \\ 3 & 2 & 1 \end{pmatrix}; \begin{pmatrix} 1 & a & b \\ 0 & 1 & c \\ 0 & 0 & 1 \end{pmatrix}; \begin{pmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{pmatrix}.$$

6. Find matrix of (a) (orthogonal) projection onto plane $3x + 2y - z = 0$; (b) (orthogonal) projection onto line $X = t(1, 0, -7)^\top$; (c) symmetry with respect to line $X = t(-1, 2, 1)^\top$.
7. Write down matrices of rotation by angle θ around x axis and around y axis. For $\theta = \pi/2$ compute superposition of those rotations in two possible orders.
8. Find matrix of rotation by angle $2\pi/3$ around line $x = y = z$. (There are two such rotations (depending on orientation); choose one.)
9. Let $F : \mathbf{R}^2 \rightarrow \mathbf{R}^3$ and $G : \mathbf{R}^3 \rightarrow \mathbf{R}^2$ be linear transformations
 - a) Prove that F is not onto (surjective).
 - b) Prove that G is not injective.
 - c) Prove that $F \circ G$ is not invertible.
10. Give examples of linear transformations $F, G : \mathbf{R}^3 \rightarrow \mathbf{R}^3$, such that (a) $\ker(F) \subset \text{Im}(F)$ (b) $\text{Im}(G) \subset \ker(G)$. Try to find both trivial and nontrivial examples.
11. Give example of linear transformation $F : \mathbf{R}^3 \rightarrow \mathbf{R}^3$, which has a plane as an image, kernel is a line and angle between kernel and image is 60° . Write down matrix of this transformation.
12. It is known that $F, G, H : \mathbf{R}^3 \rightarrow \mathbf{R}^3$ are linear transformations such that $F \circ G \circ H$ is surjective, $\det(G) = -4$, $H = F \circ G \circ F$. Prove that F is injective.

13. Prove: if $N^3 = 0$, then $(I + N)^{-1} = I - N + N^2$. Use this formula to compute $\begin{pmatrix} 1 & 2 & 5 \\ 0 & 1 & 7 \\ 0 & 0 & 1 \end{pmatrix}^{-1}$.

14. Are the following formulas true (for invertible 3×3 matrices): $(MN)^{-1} = M^{-1}N^{-1}$, $(M + N)^{-1} = M^{-1} + N^{-1}$, $\det(aM) = a \det(M)$, $\det(M + N) = \det(M) + \det(N)$?

15. Prove that for every vector $A \in \mathbf{R}^3$ transformation M_A given by formula $M_A(X) = A \times X$ is linear. Write down its matrix in terms of coordinates of A .

16. Compute determinant of matrix $\begin{pmatrix} 121 & -248 \\ -321 & 625 \\ 144 & -91 \end{pmatrix} \begin{pmatrix} 321 & 231 & 123 \\ -619 & 26 & -17 \end{pmatrix}$. Hint: answer is immediate, without computation.

17. Let $M, N \in M_{3 \times 3}$. It is known that $\det(MN) \neq 0$. Prove that M i N are invertible.

18. Let $F : \mathbf{R}^3 \rightarrow \mathbf{R}^3$ be a linear transformation. Prove: if $\ker(F)$ is one point/a line/a plane/ \mathbf{R}^3 , then $\text{Im}(F)$ is \mathbf{R}^3 /a plane/a line/one point, respectively.